

4.4 (Pool)

Similarity and Diagonalization

Consider the matrices

$$A = \begin{bmatrix} -2 & 12 \\ -1 & 5 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 4 & 3 \\ 2 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} 13 & 17 \\ -6 & -8 \end{bmatrix}$$

We can establish a relationship between

A and D and

B and C.

Using the matrix

$$P = \begin{bmatrix} 3 & 4 \\ 1 & 1 \end{bmatrix}$$

But first, we will compute P^{-1}

$$P^{-1} = \frac{1}{\underset{\text{ad-bc}}{3-4}} \begin{bmatrix} 1 & -4 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} -1 & 4 \\ 1 & -3 \end{bmatrix}$$

Now, notice that

$$\begin{aligned} P^{-1}AP &= \begin{bmatrix} -1 & 4 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} -2 & 12 \\ -1 & 5 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} -2 & 8 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} = D \end{aligned}$$

or

$$\boxed{P^{-1}AP = D}$$

and

$$\begin{aligned} P^{-1}BP &= \begin{bmatrix} -1 & 4 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} 4 & 3 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 4 & 1 \\ -2 & 0 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 13 & 17 \\ -6 & -8 \end{bmatrix} = C \end{aligned}$$

or

$$\boxed{P^{-1}BP = C}$$

Definition $A_{n \times n}, B_{n \times n}$

A is similar to B if there is an invertible $P_{n \times n}$ such that

$$P^{-1}AP = B \quad (3.1)$$

and we denote this relationship as

$$A \sim B.$$

An easy alternative to say that $A \sim B$ is to write (3.1) in its equivalence form:

$$AP = PB \quad \left(\text{How is this equation obtained?} \right)$$

Theorem 4.21 $A_{n \times n}, B_{n \times n}$ and $C_{n \times n}$

$$i) A \sim A, \quad ii) A \sim B \Rightarrow B \sim A.$$

$$iii) A \sim B \text{ and } B \sim C \Rightarrow A \sim C.$$

Proof. (Easy).

Thm 4.2.2

1) $A_{n \times n}$ and $B_{n \times n}$

2) $A \sim B$.

then,

i) $\det A = \det B$

ii) A invertible if and only if B is invertible

iii) A and B have the same rank.

iv) A and B have the same characteristic polyn.

v) A and B have the same eigenvalues.

vi) $A^m \sim B^m$, for all integers $m \geq 0$.

vii) If A is invertible, then $A^m \sim B^m$
for all integers m .

Proof:-

$$\begin{aligned} \text{i) } \det B &= \det(P^{-1}AP) = \det(P^{-1}) \det A \det P \\ &= \frac{1}{\det P} \det A \det P = \det A. \end{aligned}$$

ii) Since $\det A = \det B$

$$\begin{aligned} \text{then } \det A \neq 0 &\Leftrightarrow \det B \neq 0 \\ &\Downarrow \\ &\Downarrow A \text{ inv.} \quad \Leftrightarrow \quad B \text{ inv.} \end{aligned}$$

$$\begin{aligned} \text{iii) } \det(B - \lambda I) &= \det(P^{-1}AP - \lambda I) = \det(P^{-1}AP - \lambda P^{-1}I P) \\ &= \det(P^{-1}(A - \lambda I)P) \stackrel{(i)}{=} \det(A - \lambda I) \end{aligned}$$

$B \sim C$ and $A \sim D$.

There is an important difference between C and D

THIS IS D is diagonal.

Why is that an advantage?

Because A is similar to a diagonal matrix D , it receives a special name. This is the topic of the next definitions and theorems.

5.3 Diagonalization (*)

Consider

$$A = \begin{bmatrix} 0 & -1 & -1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix}$$

and

$$P = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix}$$

Compute the product: $P^{-1}AP$.

$$P^{-1}AP = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 & -1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = D \text{ (diagonal matrix)}$$

It can be shown (DO IT!) that

$\lambda_1 = 0$ is an eigenvalue with corresp. eigenvector $\vec{u} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$

$\lambda_2 = 1$ " " " " " " eigenvectors

$$\vec{v}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \text{ and } \vec{v}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

(*) Remark: In this section, we will consider matrices with real eigenvalues only. However, they may be repeated.

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This implies

$$P = [\vec{u} \ \vec{v}_1 \ \vec{v}_2] = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

And

$$D = P^{-1}AP = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Def.

A matrix $A_{n \times n}$ such that there exists P invertible matrix satisfying

$$P^{-1}AP = D \text{ (diagonal matrix)} \quad (2.1)$$

is said to be diagonalizable.

From the previous example we arrive to two important conclusion

- 1) A good candidate for an invertible matrix P satisfying (2.1) is a matrix whose columns are n linearly independent eigenvectors.
- 2) The diagonal matrix D has the eigenvalues along the diagonal.

Computing Eigenvalues and Eigenvectors of

$$A = \begin{bmatrix} 0 & -1 & -1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix}$$

$$|A - \lambda I| = 0 \iff \begin{vmatrix} -\lambda & -1 & -1 \\ 1 & 2-\lambda & 1 \\ -1 & -1 & -\lambda \end{vmatrix} = 0$$

$$\iff 0 = -\lambda \begin{vmatrix} 2-\lambda & 1 \\ -1 & -\lambda \end{vmatrix} + (-1)(-1)^3 \begin{vmatrix} 1 & 1 \\ -1 & -\lambda \end{vmatrix} + (-1) \begin{vmatrix} 1 & 2-\lambda \\ -1 & -1 \end{vmatrix}$$

$$= -\lambda (\lambda(\lambda-2)+1) + (-\lambda+1) - (-1+2-\lambda) =$$

$$= -\lambda^2(\lambda-2) - \cancel{\lambda} + \cancel{\lambda} + 1 - \cancel{2} + \cancel{\lambda} =$$

$$= \lambda(-\lambda(\lambda-2) - \underline{1}) = \lambda(-\lambda^2 + 2\lambda - 1)$$

$$= -\lambda(\lambda^2 - 2\lambda + 1) = -\lambda(\lambda-1)^2$$

or $\boxed{\lambda(\lambda-1)^2 = 0}$ characteristic equation.

$$\lambda_1 = 0, \quad \lambda_2 = 1 \text{ (algebraic multiplicity 2)}$$

Finding eigenvectors:

a) $\lambda_1 = 0$ $(A - \lambda I)\vec{x} = \vec{0} \Leftrightarrow A\vec{x} = \vec{0}.$

or augmented matrix:

$$\left[\begin{array}{ccc|c} 0 & -1 & -1 & 0 \\ 1 & 2 & 1 & 0 \\ -1 & -1 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ -1 & -1 & 0 & 0 \\ 0 & -1 & -1 & 0 \end{array} \right] \sim$$

$$\sim \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & -1 & -1 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{array}{l} \boxed{x_2 = -x_3} \\ x_1 = -2x_2 - x_3 \\ x_1 = 2x_3 - x_3 = x_3 \\ \text{or } \boxed{x_1 = x_3} \end{array}$$

Then eigenvectors for $\lambda_1 = 0$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_3 \\ -x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \checkmark$$

$$\text{Basis for Eigenspace of } \lambda_1 = 0 = \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

b) $\lambda_2 = 1$ (algebraic multiplicity 2)

$$(A - \lambda_2 I) \vec{x} = \vec{0} \Leftrightarrow \boxed{(A - I) \vec{x} = \vec{0}} \quad \text{Solve this linear syst.}$$

or augmented matrix

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 1 & 1 & 1 & 0 \\ -1 & -1 & -1 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$x_1 = -x_2 - x_3 \Rightarrow$ Free Variables
Eigenvectors are:

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

then

$$E_{\lambda_2=1} = \left\{ \vec{x} \in \mathbb{R}^3 : \vec{x} = t \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, t, s \in \mathbb{R} \right\}$$

This implies geometric multiplicity 2.

Thm 5 Diagonalization Thm.

A matrix $A_{n \times n}$ is diagonalizable. It means there exists P invertible such that

$$P^{-1}AP = D \text{ (diagonal matrix)}$$

if and only if A has n linearly independent eigenvectors.

It will be shown that Columns of P are n linearly independent eigenvectors of A and D is a diagonal matrix with the corresponding eigenvalues along the diagonal.

Before proving this theorem observe the following:

If $P = [\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n]$, $A_{n \times n}$, and

$$D = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ & & \ddots & \\ 0 & & & \lambda_n \end{bmatrix}$$

(diagonal matrix)

Then,

$$AP = A[\vec{v}_1 \ \dots \ \vec{v}_n] = [A\vec{v}_1 \ A\vec{v}_2 \ \dots \ A\vec{v}_n] \quad (3.1)$$

And

$$PD = [\vec{v}_1 \ \dots \ \vec{v}_n]D = P \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} = [\lambda_1 \vec{v}_1 \ \lambda_2 \vec{v}_2 \ \dots \ \lambda_n \vec{v}_n] \quad (3.2)$$

Proof Thm 5. -

$A_{n \times n}$ diagonalizable $\stackrel{\text{definition}}{\iff}$ There exists $P = [\vec{v}_1 \vec{v}_2 \dots \vec{v}_n]$
invertible such that $P^{-1}AP = D = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \iff$
There exists P invertible such that $AP = PD$

(3.1), (3.2)

$$\iff [A\vec{v}_1 \ A\vec{v}_2 \ \dots \ A\vec{v}_n] = [\lambda_1 \vec{v}_1 \ \lambda_2 \vec{v}_2 \ \dots \ \lambda_n \vec{v}_n]$$

And $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent.

$$\iff A\vec{v}_1 = \lambda_1 \vec{v}_1, \ A\vec{v}_2 = \lambda_2 \vec{v}_2, \dots, \ A\vec{v}_n = \lambda_n \vec{v}_n$$

and $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is lin. independent

$$\iff A \text{ has } n \text{ linearly independent eigenvectors}$$

$\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$, with corresponding eigenvalues
 $\lambda_1, \lambda_2, \dots, \lambda_n$ (possibly repeated).

Thm 5 suggests a method to diagonalize
a matrix A if possible. (Review previous example).

- 1) Find eigenvalues of $A: \lambda_1, \lambda_2, \dots, \lambda_n$ (possibly repeated)
 $\quad \quad \quad \mapsto \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$
- 2) Find n linearly independent eigenvectors of A ,
 (if possible). Otherwise, A is not diagonalizable
 according to thm 5.
- 3) Construct P from eigenvectors obtained in step 2.

More precisely, define

$$P = [\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n]$$

Clearly, P is invertible because the
 set of eigenvectors $S = \{\vec{v}_1, \dots, \vec{v}_n\}$ is lin. indep.

And also

$$P^{-1}AP = D = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

where $\lambda_1, \dots, \lambda_n$ are the eigenvalues ^{of A} corresponding
 to $\vec{v}_1, \dots, \vec{v}_n$ (possibly repeated).

Thm 2 (Section 5.1)

If $A_{n \times n}$ matrix is such that

$$A \vec{v}_1 = \lambda_1 \vec{v}_1, \dots, A \vec{v}_r = \lambda_r \vec{v}_r, \quad \vec{v}_i \neq \vec{0}, \quad i=1,2,\dots,r \quad \nearrow \text{eigenvectors}$$

and $\lambda_1, \dots, \lambda_r$ are distinct eigenvalues,

then the set $\{\vec{v}_1, \dots, \vec{v}_r\}$ is linearly independent.

Proof. -

Want to prove

$$\text{If } C_1 \vec{v}_1 + C_2 \vec{v}_2 + \dots + C_r \vec{v}_r = \vec{0} \Rightarrow C_1 = 0, \dots, C_r = 0.$$

So, start assuming

$$C_1 \vec{v}_1 + C_2 \vec{v}_2 + \dots + C_r \vec{v}_r = \vec{0} \quad (6.1)$$

and multiply by A both sides

$$A(C_1 \vec{v}_1 + \dots + C_r \vec{v}_r) = A \vec{0} = \vec{0}$$

Using matrix operations and the hypothesis λ_i 's and $\vec{v}_i$'s eigenval. eigenvect.

$$C_1 A \vec{v}_1 + \dots + C_r A \vec{v}_r = \vec{0} \Leftrightarrow C_1 \lambda_1 \vec{v}_1 + \dots + C_r \lambda_r \vec{v}_r = \vec{0}$$

Multiplying Equ. (6.1) $\times \lambda_1$ and subtracting $-C_1 \lambda_1 \vec{v}_1 - \dots - C_r \lambda_1 \vec{v}_r = 0$

(*)

$$\Rightarrow \boxed{C_2 = 0, \dots, C_r = 0}, \text{ Since } \lambda_2 \neq \lambda_1, \dots, \lambda_r \neq \lambda_1 \text{ and } \vec{v}_2, \dots, \vec{v}_r \neq \vec{0}.$$

Substitution into (6.1) $\Rightarrow \boxed{C_1 = 0}.$

✓ (*) This conclusion requires an induction hypothesis. NOT COMPLETE!
But, very easy to do!

Theorem 6

Any $A_{n \times n}$ matrix with n distinct eigenvalues: $\lambda_1, \dots, \lambda_n$ is diagonalizable.

Proof:- Trivial consequence of thm 2 and thm 5.

If A has n distinct eigenvalues $\xRightarrow{\text{Thm 2}}$ The set $S = \{\vec{v}_1, \dots, \vec{v}_n\}$ of the eigenvectors corresponding to the n distinct eigenvalues is linearly independent.

$\xRightarrow{\text{Thm 5}}$ A is diagonalizable.

Why the reciprocal statement:

A diagonalizable $\Rightarrow A$ has n distinct eigenvalues
is not TRUE. See our previous example!

Thm 4.24

1) $A_{n \times n}$ and $\lambda_1, \dots, \lambda_n$ distinct eigenvalues of A .

2) B_i is a basis for Eigenspace λ_i , $i=1, \dots, n$

Then,

$$B = B_1 \cup B_2 \cup \dots \cup B_n$$

is a linearly independent set of vectors.

Remark: B is a set formed by the basis vectors for all of the eigenspaces.

Consider

Ex #13 (5.1) $A = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$

Determine if A is diagonalizable or not.

1) First compute eigenvalues of A

$$|A - \lambda I| = 0 \Leftrightarrow \begin{vmatrix} 4-\lambda & 0 & 1 \\ -2 & 1-\lambda & 0 \\ -2 & 0 & 1-\lambda \end{vmatrix} = 0$$

$$\Leftrightarrow (4-\lambda)(1-\lambda)(1-\lambda) - [-2(1-\lambda)] = 0$$

$$\Leftrightarrow (1-\lambda) \left[(4-\lambda)(1-\lambda) + 2 \right] = (1-\lambda) \left[\lambda^2 - 5\lambda + \frac{4+2}{6} \right]$$

$$= (1-\lambda) \left[(\lambda-3)(\lambda-2) \right] = 0$$

$$\Leftrightarrow \lambda_1 = 1, \lambda_2 = 2, \lambda_3 = 3$$

Since $A_{3 \times 3}$ has 3 distinct eigenvalues by thm 6

A is diagonalizable. ✓

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If we also would like to find a matrix P such that

$$P^{-1}AP = D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

We need to find the eigenvectors associated to each eigenvalue

$$\text{For } \lambda_1 = 1 \quad \vec{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix},$$

$$\text{For } \lambda_2 = 2 \quad \vec{v}_2 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}$$

$$\text{For } \lambda_3 = 3 \quad \vec{v}_3 = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Then

$$P = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \\ 0 & -1 & -1 \\ 1 & 2 & 1 \\ 0 & 2 & 1 \end{bmatrix}?$$

order of the columns is important

Why we don't need to verify that the set $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is linearly independent?

Also,

$$P^{-1} = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ -2 & 0 & -1 \end{bmatrix}$$

$$P^{-1}A = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ -2 & 0 & -1 \end{bmatrix} \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & -1 \\ 2 & 0 & 2 \\ -6 & 0 & -3 \end{bmatrix}$$

$$(P^{-1}A)P = \begin{bmatrix} 0 & 1 & -1 \\ 2 & 0 & 2 \\ -6 & 0 & -3 \end{bmatrix} \begin{bmatrix} 0 & -1 & -1 \\ 1 & 2 & 1 \\ 0 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$